# Being Efficient in Time, Space, and Workload: a Self-stabilizing Unison and its Consequences

#### S. Devismes, D. Ilcinkas, C. Johnen and F. Mazoit

Université de Picardie Jules Verne and Université de Bordeaux, France

4 D K 4 B K 4 B K 4

March 3, 2025

Many kinds of "daemons"

э

イロン 不聞 とくほとう ほとう

Many kinds of "daemons"

Synchronous daemon

At each step, **all** nodes are synchronously activated.

< ロ > < 同 > < 回 > < 回 > < 回 > <

Many kinds of "daemons"

Synchronous daemon

At each step, all nodes are synchronously activated.

Distributed fair daemon

At each step, **some** nodes are activated.

イロト イヨト イヨト ・

Many kinds of "daemons"

## Synchronous daemon

At each step, all nodes are synchronously activated.

## Distributed fair daemon

At each step, **some** nodes are activated.

No contraints other that nodes cannot "starve".

- 4 回 ト - 4 回 ト

Many kinds of "daemons"

### Synchronous daemon

At each step, all nodes are synchronously activated.

### Distributed fair daemon

At each step, **some** nodes are activated.

No contraints other that nodes **cannot** "starve".

### Distributed unfair daemon

At each step, **some** nodes are activated.

Many kinds of "daemons"

### Synchronous daemon

At each step, all nodes are synchronously activated.

### Distributed fair daemon

At each step, **some** nodes are activated.

No contraints other that nodes cannot "starve".

### Distributed unfair daemon

At each step, **some** nodes are activated.

No constraints. Thus nodes can "starve".

(4 何) トイヨト イヨト

# Self-Stabilization & Unison

Self-Stabilization

The initial configuration is arbitrary.

Models error recovery after "transient" faults.<sup>1</sup>

<sup>1</sup>TCP is a self-stabilizing heuristic.

< □ > < 同 > < 回 > < 回 > < 回 >

# Self-Stabilization & Unison

## Self-Stabilization

The initial configuration is arbitrary.

Models error recovery after "transient" faults.<sup>1</sup>

## (Asynchronous) Unison

Each node has a **local clock**. Neighboring clocks differ by  $\leq 1$  increment. All clocks increase infinitely often.

<sup>1</sup>TCP is a self-stabilizing heuristic.

- ロ ト ・ 同 ト ・ 三 ト ・ 三 ト - -

# Self-Stabilization & Unison

## Self-Stabilization

The initial configuration is arbitrary.

Models error recovery after "transient" faults.<sup>1</sup>

## (Asynchronous) Unison

Each node has a **local clock**. Neighboring clocks differ by  $\leq 1$  increment. All clocks increase infinitely often.

#### A consequence

Run a self-stabilizing algorithm under a synchronous daemon.

・ロト ・ 同ト ・ ヨト ・ ヨト

<sup>&</sup>lt;sup>1</sup>TCP is a self-stabilizing heuristic.

# Being Efficient in Time, Space, and Workload : a Self-stabilizing Unison and its Consequences

イロト イヨト イヨト イヨト

# Being Efficient in Time, Space, and Workload : a Self-stabilizing Unison and its Consequences

(日) (四) (日) (日) (日)

Round complexity

Captures the "execution time".

э

イロン イヨン イヨン

Round complexity

Captures the "execution time".

relevant parameter: D (diameter of G).

3

イロト イポト イヨト イヨト

Round complexity

Captures the "execution time".

relevant parameter: D (diameter of G).

Move complexity

Captures the "total workload".

(日)

Round complexity

Captures the "execution time".

relevant parameter: D (diameter of G).

Move complexity

Captures the "total workload".

relevant parameter: n (the number of nodes of G).

イロト イヨト イヨト ・

Round complexity

Captures the "execution time".

relevant parameter: D (diameter of G).

### Move complexity

Captures the "total workload". relevant parameter: n (the number of nodes of G).

Space complexity

Captures the local memory requirement.

イロト 不得 トイヨト イヨト

3

ヘロア 人間 アメヨア 人間 アー

Atomic State Model: Classical in self-stabilization

[Dijkstra, 1974]

э

イロト イヨト イヨト イヨト

Atomic State Model: Classical in self-stabilization

[Dijkstra, 1974]

Locally shared memory model with composite atomicity Each node u has a **local state**.

< □ > < 同 > < 回 > < 回 > < 回 >

Atomic State Model: Classical in self-stabilization

[Dijkstra, 1974]

Locally shared memory model with composite atomicity

Each node *u* has a **local state**.

When moving, u atomically

- reads the states of its neighbors,
- changes its state.

イロト イヨト イヨト

Atomic State Model: Classical in self-stabilization

[Dijkstra, 1974]

Locally shared memory model with composite atomicity

Each node u has a **local state**.

When moving,  $\boldsymbol{u}$  atomically

- reads the states of its neighbors,
- changes its state.

Variants

- Nodes receive sets/multisets/... of states
- Nodes identified or not identified
- Ports labeled or **not labeled**



Finite memory implies the knowledge of  $N \ge n$  or  $B \ge D$ .

<sup>2</sup>Not in Atomic State Model

Mazoit

(日)

э

	Rounds	Moves	Space	Daemon
Couvreur et al. $(ICDCS'92)^2$	?	?	$\Theta(\log N)$	unfair
Awerbuch et al. $(STOC'93)^2$	O(D)	?	$\infty$	unfair

Finite memory implies the knowledge of  $N \ge n$  or  $B \ge D$ .

<sup>2</sup>Not in Atomic State Model

Mazoit

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <



Finite memory implies the knowledge of  $N \ge n$  or  $B \ge D$ .

<sup>2</sup>Not in Atomic State Model

Mazoit

ヘロト 人間ト 人間ト 人間ト

э



<sup>2</sup>Not in Atomic State Model

Mazoit

(日)

Finite memory implies the knowledge of  $N \ge n$  or  $B \ge D$ .

	Rounds	Moves	Space	Daemor
Couvreur et al. $(ICDCS'92)^2$	?	?	$\Theta(\log N)$	unfair
Awerbuch et al. $(STOC'93)^2$	O(D)	?	$\infty$	unfair
Boulinier et al. (PODC'04)	O(n)	$O(Dn^3)$	$\Theta(\log N)$	unfair
Emek et Keren. (PODC'21)	$O(B^3)$	unbounded	$\Theta(\log B)$	fair
This paper	O(D)	$O(n^3)$	$\Theta(\log B)$	unfair

<sup>2</sup>Not in Atomic State Model

Mazoit

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Finite memory implies the knowledge of  $N \ge n$  or  $B \ge D$ .

# Consequences

	Rounds	Moves	Space
Unison	2D + 2	$O\bigl(\min(n^2B,n^3)\bigr)$	$\lceil \log B \rceil + 2$

With  $B \geq 2D+2$ 

Mazoit

# Consequences

	Rounds	Moves	Space
Unison	2D + 2	$O\bigl(\min(n^2B,n^3)\bigr)$	$\lceil \log B \rceil + 2$
Synchronizer	5D+3T	$O(\min(n^2B, n^3) + nT)$	$2M + \lceil \log B \rceil + 2$

 $\label{eq:synchronizer} \begin{array}{l} \mbox{Synchronizer input: self-stabilizing algorithm $\mathcal{A}$} \\ T, \ M = \mbox{synchronous time, space of $\mathcal{A}$}. \end{array}$ 

With  $B \ge 2D + 2$ 

Mazoit

(日) (四) (日) (日) (日)

# Consequences

	Rounds	Moves	Space
Unison	2D + 2	$O\bigl(\min(n^2B,n^3)\bigr)$	$\lceil \log B \rceil + 2$
Synchronizer	5D+3T	$O\big(\min(n^2B, n^3) + nT\big)$	$2M + \lceil \log B \rceil + 2$

Synchronizer input: self-stabilizing algorithm  $\mathcal{A}$ T, M = synchronous time, space of  $\mathcal{A}$ .

Problem	Rounds	Moves	Space
BFS tree in rooted networks	O(D)	$O(n^3)$	$\Theta(\log B + \log \Delta)$
BFS tree in identified networks	O(D)	$O(n^3)$	$\Theta(\log N)$
Leader election	O(D)	$O(n^3)$	$\Theta(\log N)$
$O(\frac{n}{k})$ -clustering	O(D)	$O(n^3)$	$\Theta(\log k + \log N)$

With  $B \ge 2D + 2$  and  $N \ge n$ 

▲ロト ◆ □ ト ◆ □ ト ◆ □ ト ◆ □ ト ◆ □ ト ◆ □ ト ◆ □ ト ◆ □ ト ◆ □ ト ◆ □ ト ○ Q ○
March 3, 2025 8/9

Mazoit

## Questions?

State: 
$$p.s \in \{C, E\}, p.c \in \begin{cases} [-B, B) & \text{if } p.s = C \\ [-B, 0) & \text{if } p.s = E \end{cases}$$

Predicates:

$$\begin{aligned} \operatorname{root}(p) &:= \left( p.s = E \land \neg (\exists q \in N(p), \ q.s = E \land q.c < p.c) \right) \lor \\ \left( p.s = C \land \exists q \in N(p), \ (q.c \ge p.c+2) \land \neg (p.c = 0 \land q.c = B-1) \right) \end{aligned}$$
$$activeRoot(p) &:= \operatorname{root}(p) \land (p.c \ne -B \lor p.s = C) \\ errPropag(p,i) &:= i < 0 \land \exists q \in N(p), \ q.s = E \land q.c < i < p.c \\ \operatorname{canClearE}(p) &:= p.s = E \land \forall q \in N(p), \ (|q.c - p.c| \le 1 \land (q.c \le p.c \lor q.s = C)) \\ updatable(p) &:= p.s = C \land \forall q \in N(p), \ q.c \in \{p.c, p.c \oplus_B 1\} \end{aligned}$$

Rules:

$$\begin{array}{ll} R_R: activeRoot(p) & \rightarrow (p.s, p.c) := (E, -B) \\ R_P(i): errPropag(p, i) \rightarrow (p.s, p.c) := (E, i) \end{array} \begin{array}{ll} R_C: canClearE(p) \rightarrow p.s := C \\ R_U: updatable(p) & \rightarrow p.c := p.c \oplus_B 1 \end{array}$$

 $R_R$ : highest priority,  $R_P(i)$  higher priority that  $R_P(i+l)$  for l > 0.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <