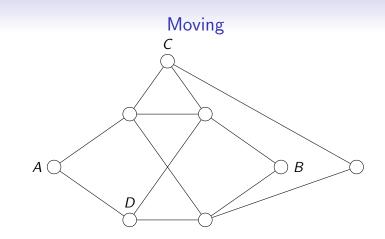
Tight Approximation and Kernelization Bounds for Vertex-Disjoint Shortest Paths

Matthias Bentert Fedor V. Fomin Petr A. Golovach

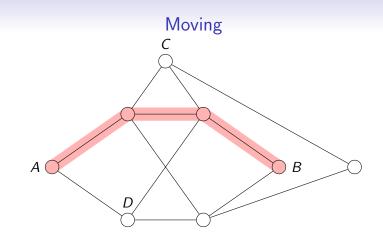
Univerity of Bergen

March 05 2025

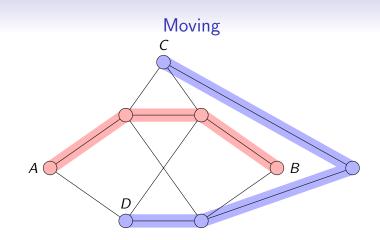
42nd International Symposium on Theoretical Aspects of Computer Science (STACS)



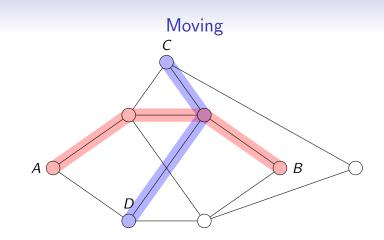
Tight Bounds for Disjoint Shortest Paths



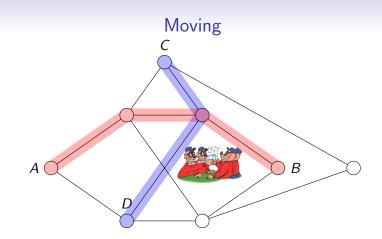
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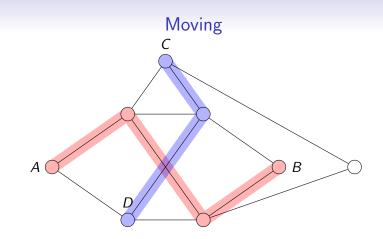
Tight Bounds for Disjoint Shortest Paths



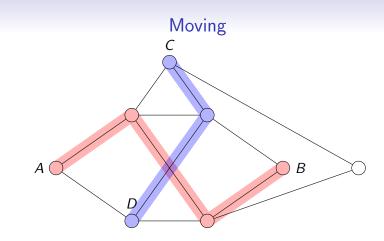
Tight Bounds for Disjoint Shortest Paths



Tight Bounds for Disjoint Shortest Paths



Tight Bounds for Disjoint Shortest Paths



Disjoint Shortest Paths

Input: An undirected graph G and vertex pairs $(s_i, t_i)_{i \in \{1, 2, ..., k\}}$.

Task: Connect as many terminal pairs as possible via vertex-disjoint shortest s_i - t_i -paths.

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Tight Bounds for Disjoint Shortest Paths

• 2 Disjoint Shortest Paths

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Tight Bounds for Disjoint Shortest Paths

- 2 Disjoint Shortest Paths
 - undirected graphs: $O(n^8)$, $O(n^6)$, O(nm), O(n+m) time

[Eilam-Tzoreff. Discrete Applied Mathematics 1998]

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[B, Nichterlein, Renken, and Zschoche. SIAM Journal on Discrete Mathematics 2023]

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[Lochet. SODA 2021]

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O(nm⁵) time on directed graphs

• k Disjoint Shortest Paths

- solvable in $n^{O(k^{5^k})}$ time on undirected graphs
- solvable in $n^{O((k+1)!)}$ time and W[1]-hard wrt. k

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• no $(2 - \varepsilon)$ -approximation in $f(k)n^{o(k)}$ time assuming gap-ETH

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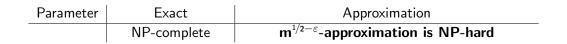
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[Chitnis, Thomas, and Wirth. WAOA 2024] solvable in polynomial time on directed planar graphs if all terminals are incident to two faces (even min-sum) [Coli n de Verdière and Schrijver. ACM TALG 2011]

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Tight Bounds for Disjoint Shortest Paths



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Tight Bounds for Disjoint Shortest Paths

Parameter	Exact	Approximation
	NP-complete	$m^{1/2-\varepsilon}$ -approximation is NP-hard
k	XP and W[1]-hard	$c \cdot k$ -approximation for any c no o(k)-approximation in f(k) \cdot poly(n) time

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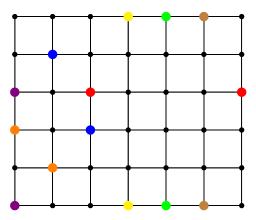
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Tight Bounds for Disjoint Shortest Paths

Upper and Lower (FPT) Approximation Bounds

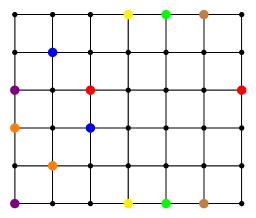
• find terminal pair of minimum distance



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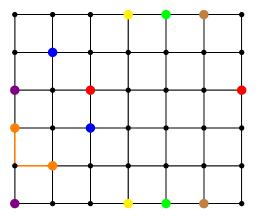
- find terminal pair of minimum distance
- connect by any shortest path



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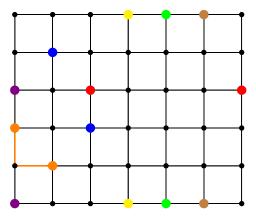
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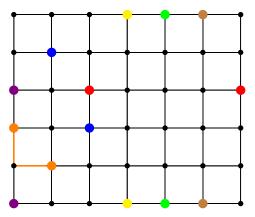
- find terminal pair of minimum distance
- connect by any shortest path
- remove all vertices in the path and all terminal pairs whose distance increases



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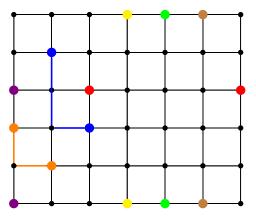
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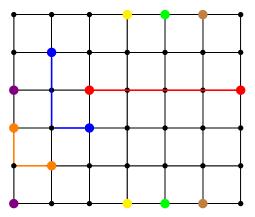
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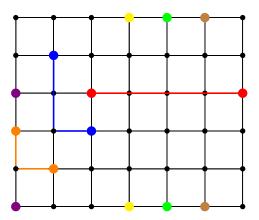
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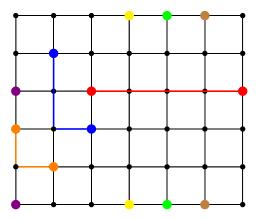
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- if dist(s_i, t_i) + 1 ≤ √ℓ: remove at most √ℓ terminal pairs in optimal solution



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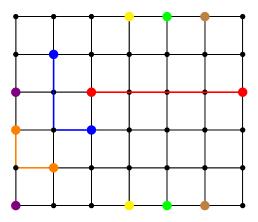
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- if dist(s_i, t_i) + 1 ≤ √ℓ: remove at most √ℓ terminal pairs in optimal solution
- if dist(s_i, t_i) + 1 > √ℓ: at most √ℓ terminal pairs left in optimal solution



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- connect by any shortest path
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- if dist(s_i, t_i) + 1 > √l: at most √l terminal pairs left in optimal solution
 √l-approximation in polynomial time



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Tight Bounds for Disjoint Shortest Paths

The General Idea for excluding $m^{1/2-\varepsilon}$ -approximations

• Computing a $n^{1-\varepsilon}$ -approximation for CLIQUE is NP-hard.

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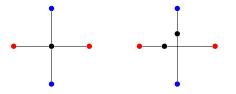
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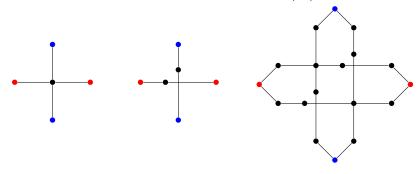


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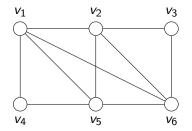
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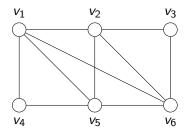
The Reduction

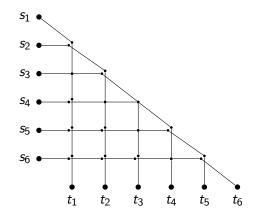


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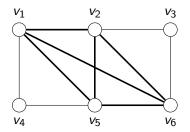


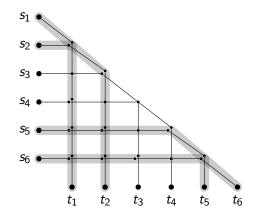


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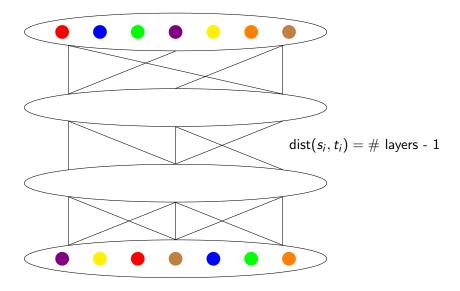


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Tight Bounds for Disjoint Shortest Paths

Excluding Polynomial Kernels

A Special Case



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input: t instances I_1, I_2, \ldots, I_t of special case all with same number of layers and terminal pairs

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 - $|I| \leq \operatorname{poly}(\sum_{i=1}^{t} |I_i|)$
 - $\ell \leq \operatorname{poly}(\max_{i=1}^{t} |I_i| + \log(t))$

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approach: iteratively combine two instances such that number of layers increase by O(k)

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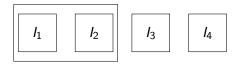


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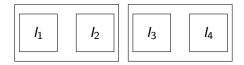


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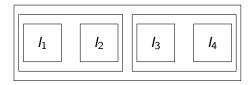


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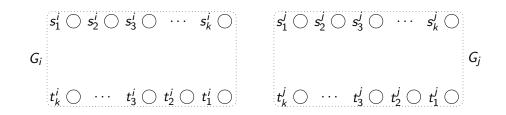
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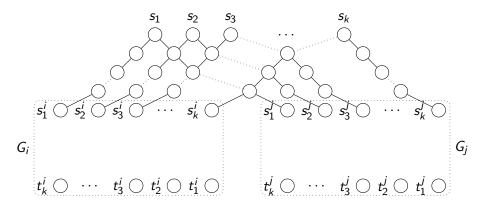
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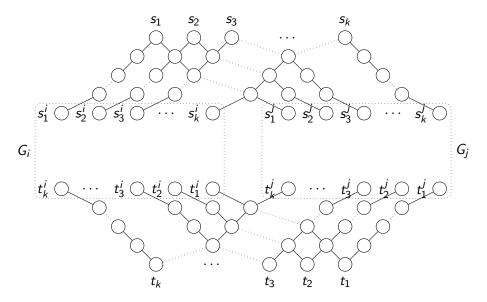
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• FPT approximation for structural parameters?

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10 /

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- FPT approximation for structural parameters?
- poly(ℓ)-size lossy kernels with approximation factors in $o(\sqrt{\ell})$ (or even constant)?

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Thank you.

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